#### Numerical simulation of turbulence at lower costs: regularization modeling

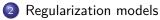
F.Xavier Trias\*, Andrey Gorobets\*,\*, Manel Soria\*, Assensi Oliva\*

\*Heat and Mass Transfer Technological Center Technical University of Catalonia \*Keldysh Institute of Applied Mathematics of RAS, Russia

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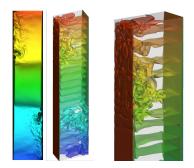
- 3 Discretizing  $C_n$  regularizations
- 4 Results for a DHC



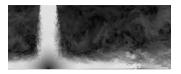
#### DNS of turbulent incompressible flows on MareNostrum

Main features of the DNS code:

- Structured staggered grids
- High-order symmetry-preserving schemes
- Fully-explicit second-order time-integration method
- Poisson solver for 2.5D problems: FFT + PCG
- Hybrid MPI+OpenMP parallelization

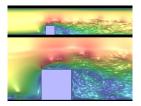


Air-filled differentially heated cavity at  $Ra = 10^{11}$  (111M grid points)



Plane impingement jet at Re = 20000 (102M grid points)

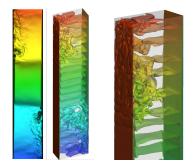
#### DNS of turbulent incompressible flows on MareNostrum



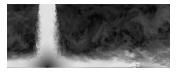
Wall-mounted cube at Re = 7240 (17M grid points)



Square cylinder at Re = 22000 (75M grid points)

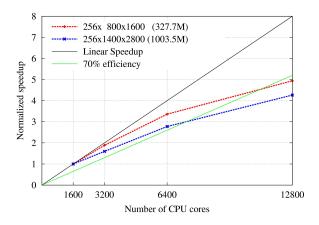


Air-filled differentially heated cavity at  $Ra = 10^{11}$  (111M grid points)



Plane impingement jet at Re = 20000 (102M grid points)

#### Scaling? Yes<sup>1</sup>, we can... but never enough



<sup>1</sup>A. Gorobets *et al.* "Hybrid MPI+OpenMP parallelization of an FFT-based 3D Poisson solver with one periodic direction" **Computers&Fluids**, (accepted)

#### Governing equations

Incompressible Navier-Stokes equations:

$$\nabla \cdot u = 0$$
  
$$\partial_t u + \mathcal{C}(u, u) = \mathcal{D}(u) - \nabla p$$

where the nonlinear convective term is given by

 $\mathcal{C}(u,\phi) = (u \cdot \nabla)\phi$ 

and the linear dissipative term is given by

$$\mathcal{D}(\phi) = \nu \Delta \phi$$

#### Regularization modeling

As the full energy spectrum cannot be computed, a **dynamically less complex mathematical formulation** is sought. We consider smooth approximations (regularizations) of the nonlinearity,

$$\partial_t u_{\epsilon} + \widetilde{\mathcal{C}}(u_{\epsilon}, u_{\epsilon}) = \mathcal{D}(u_{\epsilon}) - \nabla p_{\epsilon}$$

such approximations may fall in the Large-Eddy Simulation (LES) concept,

$$\partial_t ar{u}_\epsilon + \mathcal{C}(ar{u}_\epsilon, ar{u}_\epsilon) \;\; = \;\; \mathcal{D}(ar{u}_\epsilon) - 
abla ar{p}_\epsilon + \mathcal{M}_1(ar{u}_\epsilon, ar{u}_\epsilon)$$

if the filter is invertible:

$$\mathcal{M}_1(\bar{u}_{\epsilon}, \bar{u}_{\epsilon}) = \mathcal{C}(\bar{u}_{\epsilon}, \bar{u}_{\epsilon}) - \overline{\widetilde{\mathcal{C}}(u_{\epsilon}, u_{\epsilon})}$$

#### Previous regularization modelings

Leray and Navier-Stokes- $\alpha$  models

The regularization methods basically **alters the convective term** to **restrain the production of small scales** of motion.

• Leray model:

$$\partial_t u_{\epsilon} + \mathcal{C}(\bar{u}_{\epsilon}, u_{\epsilon}) = \mathcal{D}(u_{\epsilon}) - \nabla p_{\epsilon}$$

• Navier-Stokes- $\alpha$  model:

$$\partial_t u_{\epsilon} + C_r(u_{\epsilon}, \bar{u}_{\epsilon}) = \mathcal{D}(u_{\epsilon}) - \nabla \pi_{\epsilon}$$

where the  $\pi = p + u^2/2$  and the convective operator in rotational form is defined as  $C_r(u, v) = (\nabla \times u) \times v$ 

However, in doing so some of the **inviscid invariants** (kinetic energy, enstrophy in 2D and helicity in 3D) are **not conserved**.

#### Symmetry-preserving regularization models (1/2)

In order to conserve the following inviscid invariants

- Kinetic energy : (u, u)
- Enstrophy (in 2D) :  $(\omega, \omega)$
- Helicity (in 3D) :  $(\omega, u)$

where  $(a, b) = \int_{\Omega} a \cdot b d\Omega$  and  $\omega = \nabla \times u$ ; the **approximate convective operator** must be **skew-symmetric**:

$$\left(\widetilde{\mathcal{C}}(u,\phi_1),\phi_2\right) = -\left(\widetilde{\mathcal{C}}(u,\phi_2),\phi_1\right)$$

#### Symmetry-preserving regularization models (2/2)

This criterion yields the following class of approximations<sup>2</sup>,

$$\partial_t u_\epsilon + \mathcal{C}_n(u_\epsilon, u_\epsilon) = \mathcal{D}(u_\epsilon) - \nabla p_\epsilon$$

in which the convective term in smoothed according to:

where  $u' = u - \bar{u}$  and  $C_n(u, \phi) = C(u, \phi) + O(\epsilon^n)$  for any symmetric filter.

<sup>2</sup>Roel Verstappen, Computers & Fluids, 37 (7): 887-897, 2008

#### Discretizing the $C_n$ regularization modeling

The regularizations  $C_n$  are constructed in a way that the **symmetry properties** are exactly **preserved**.

Of course, the same should hold for the numerical approximations.

For this the basic ingredients are twofold:

- A symmetry-preserving spatial discretization of the original NS equations.
- A normalized self-adjoint linear filter.

#### Symmetry-preserving discretization of NS equations

The spatially discrete incompressible Navier-Stokes equations read

$$\Omega_s \frac{d\boldsymbol{u}_s}{dt} + \mathsf{C}(\boldsymbol{u}_s)\boldsymbol{u}_s = \mathsf{D}\boldsymbol{u}_s - \Omega_s \mathsf{G}\boldsymbol{p}_c ; \qquad \mathsf{M}\boldsymbol{u}_s = \boldsymbol{0}_c$$

Symmetries of underlying continuous operators must be preserved!

$$C = -C^T \longrightarrow u_s^T C u_s = 0 \text{ and } \lambda_C \in \mathbb{I}$$
  
no false dissipation, only transport!

 $D = D^{T} \quad def - \longrightarrow \quad \boldsymbol{u}_{s}^{T} D \boldsymbol{u}_{s} < 0 \text{ and } D \hat{\boldsymbol{u}}_{k} = \lambda_{D} \hat{\boldsymbol{u}}_{k} \text{ , } \lambda_{D} \in \mathbb{R}^{-}$ pure diffusion, no transport!

$$-\Omega_s \mathbf{G} = \mathbf{M}^T \longrightarrow -\boldsymbol{u}_s^T \Omega_s \mathbf{G} \boldsymbol{p}_c = 0$$
no contribution to total kinetic energy!

to preserve the continuous inviscid invariants in a discrete sense.

#### Basic properties

$$\overline{u_s} = F u_s$$

Four properties are required:

- i) Symmetry,  $\Omega_s F = (\Omega_s F)^T$
- ii)  $\mathsf{M}\boldsymbol{u}_s = \boldsymbol{0}_c \longrightarrow \mathsf{M}\boldsymbol{F}\boldsymbol{u}_s = \boldsymbol{0}_c$
- iii) Normalization, F1 = 1

iv) ... and of course, it must effectively damp the high-frequency components. **But, how much?** 

### Stopping the vortex-stretching<sup>3</sup>

Taking the curl of momentum equation the vorticity transport equation follows

$$\partial_t \omega + \mathcal{C}(u, \omega) = \mathcal{C}(\omega, u) + \mathcal{D}(\omega)$$

Let us now consider an arbitrary part of the flow domain,  $\Omega$ , with periodic boundary conditions. Then, taking the  $L^2$  innerproduct with  $\omega = \nabla \times u$  leads to the enstrophy equation

$$\frac{1}{2}\frac{d}{dt}(\omega,\omega) = (\omega,\mathcal{C}(\omega,u)) - \nu (\nabla \omega,\nabla \omega)$$

where  $(a, b) = \int_{\Omega} a \cdot b d\Omega$ . Unless, the grid is fine enough convection dominates diffusion

 $(\omega, \mathcal{C}(\omega, u)) > \nu (\nabla \omega, \nabla \omega)$ 

<sup>3</sup>F.X. Trias et al. Computers&Fluids, 39:1815-1831, 2010

#### Stopping the vortex-stretching

The vortex-stretching term can be expressed in terms of the invariant  $r = -1/3tr(S^3)$ 

$$(\omega, \mathcal{C}(\omega, u)) = 4 \int_{\Omega} r d\Omega$$
 (1)

whereas the  $L^2(\Omega)$ -norm of  $\omega$  in terms of the invariant  $q = -1/2tr(S^2)$ 

$$(\omega,\omega)=-4\int_{\Omega}qd\Omega$$

Then, the diffusive term can be bounded by

$$\nu (\nabla \omega, \nabla \omega) = -\nu (\omega, \Delta \omega) \leq -\nu \lambda_{\Delta} (\omega, \omega) = 4\nu \lambda_{\Delta} \int_{\Omega} q d\Omega \qquad (2)$$

where  $\lambda_{\Delta} < 0$  is the largest (smallest in absolute value) non-zero eigenvalue of Laplacian operator  $\Delta$  on  $\Omega$ . If we now consider that the domain is a periodic box of volume h, then  $\lambda_{\Delta} = -(\pi/h)^2$ .

#### Stopping the vortex stretching

 $\Longrightarrow$  In the present work we determine the filter width  $\epsilon$  from

$$(\omega, \mathcal{C}_4(\omega, u)) \approx f_4(\hat{g}_k(\epsilon))(\omega, \mathcal{C}(\omega, u)) \leq \nu (\nabla \omega, \nabla \omega)$$

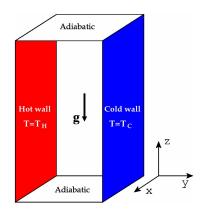
Then, recalling identity (1) and inequality (2), we propose to rewrite the previous inequality in terms of the invariants q and r

$$f_4(\hat{g}_k) = min\left\{
u\lambda_\Deltarac{m{q}}{r^+},1
ight\} \qquad ext{with} \quad r^+ = max(r,0)$$

Notice that q < 0 (dissipation) whereas r can be either positive or negative.

- Switches off  $(f_4 = 1)$  for: laminar  $(r \to 0)$ , 2D flows (r = 0) and for fine enough meshes,  $|\nu\lambda_{\Delta}q/r| \ge 1$ .
- Consistent near-wall behavior  $r \propto y^3$  and  $q \propto y^0$ .
- Consistent with the preferential vorticity alignment with the intermediate eigenvector,  $\lambda_2$  (experimentally observed)

#### Test-case: Differentially Heated Cavity



Boundary conditions:

- Isothermal vertical walls
- Adiabatic horizontal walls
- **Periodic** boundary conditions in the spanwise direction

Dimensionless governing numbers:

•  $Ra = \beta \Delta T L_z^3 g/(\alpha \nu)$ 

• 
$$\Pr = \nu/\alpha$$

• Height aspect ratio  $A_z = L_z/L_y$ 

• Depth aspect ratio 
$$A_x = L_x/L_y$$

#### DNS<sup>4,5</sup> results for $Ra = 10^{11}$ , Pr = 0.71

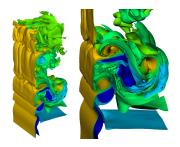


Some details about **DNS**:

- Mesh size:  $128 \times 682 \times 1278$
- $\bullet~\approx$  3 months 256 CPUs
- 4<sup>th</sup>-order symmetry-preserving scheme
- *A*<sub>z</sub> = 4

#### Complexity of the flow:

- Boundary layers
- Stratified cavity core
- Internal waves
- Recirculation areas



 $^4$  F. X. Trias *et al.* Int. Journal of Heat and Mass Transfer, 53:665-673, 2010  $^5$  F. X. Trias *et al.* Int. Journal of Heat and Mass Transfer, 53:674-683, 2010

#### Results for differentially heated cavity at $Ra = 10^{11}$

- Regularization model  $\mathcal{C}_4$  is tested.
- Two coarse meshes are considered

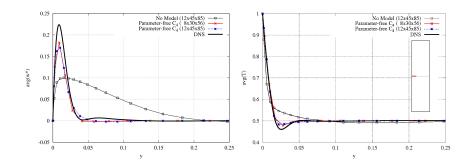
	DNS	RM1	RM2
Nx	128	12	8
Ny	682	45	30
Nz	1278	85	56

• The **discrete linear filter**<sup>6</sup> is based on polynomial functions of the discrete diffusive operator, D

<sup>6</sup>F.X. Trias and R.W.C.P. Verstappen, Computers & Fluids, 40:139-148, 2011

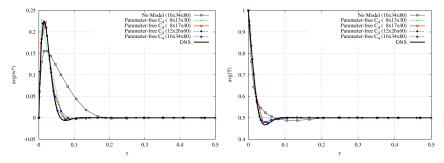
## Results for differentially heated cavity at $Ra = 10^{11}$

Profiles



Averaged vertical velocity and temperature profiles at the horizontal mid-height plane.

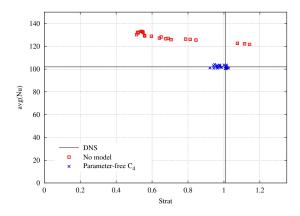
# How does the parameter-free $\tilde{C}_4$ regularization modeling behave for other grids and *Ra*-numbers?



Averaged vertical velocity and temperature profiles at the horizontal mid-height plane at  $Ra = 10^{10}$ .

Even for a **very coarse**  $8 \times 13 \times 30$  grid **reasonable results** are obtained!  $\implies$  Results for different grids show the **robustness** of the method.

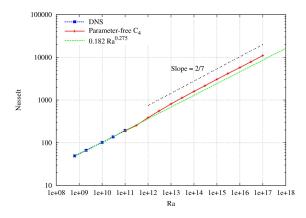
#### Challenging $C_4$ : mesh independence analysis



The overall Nusselt number and the centerline stratification for 50 randomly generated coarse grids with fixed stretching at  $Ra = 10^{10}$ .

 $8 \le N_x \le 16$ ,  $17 \le N_y \le 34$ , and  $40 \le N_z \le 80$ .

#### Performance at very high Rayleigh numbers



Meshes have been generated with the criteria of keeping the same number of points in the BL than for  $Ra = 10^{10}$ .

#### Conclusions and Future Research

The results shown illustrate the potential of the conservative parameter-free  $\widetilde{\mathcal{C}}_4$  smoothing as a new simulation shortcut.

The main advantages with respect exiting LES models can be summarized:

- **Robustnest**. As the smoothed governing equations preserve the symmetry properties of the original NS equations the solution cannot blow up (in the energy-norm, in 2D also: enstrophy-norm). It seems that even for very coarse meshes reasonably results can be obtained.
- **Universality**. No *ad hoc* phenomenological arguments that cannot be formally derived for the NS equations are used.
- The proposed method constitutes a **parameter-free turbulence model**.

# Thank you for you attention

#### Further reading about $C_4$ regularization

- Roel Verstappen, "On restraining the production of small scales of motion in a turbulent channel flow", Computers & Fluids, 37 (7): 887-897, 2008
- F. X. Trias et al., "Parameter-free symmetry-preserving regularization modeling of a turbulent differentially heated cavity", Computers & Fluids, 39:1815-1831, 2010.
- F. X. Trias and R.W.C.P. Verstappen, "On the construction of discrete filters for symmetry-preserving regularization models", Computers & Fluids, 40:139-148, 2011.